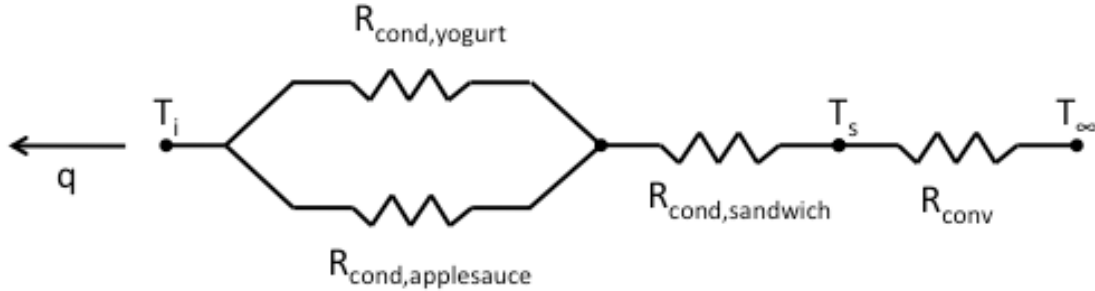


Problem 1

(a)

Assuming the interfacial temperature between sandwich and yogurt is the same as that of between sandwich and applesauce,



$$R_{cond,yogurt} = \frac{H_a}{K_y \cdot A_y} = \frac{H_a}{K_y \cdot \left(\frac{L}{2}\right) \cdot D}$$

$$R_{cond,applesauce} = \frac{H_a}{K_a \cdot A_a} = \frac{H_a}{K_a \cdot \left(\frac{L}{2}\right) \cdot D}$$

$$\frac{1}{R_{sum,parallel}} = \frac{1}{R_{cond,yogurt}} + \frac{1}{R_{cond,applesauce}} = \frac{K_y \cdot \left(\frac{L}{2}\right) \cdot D}{H_a} + \frac{K_a \cdot \left(\frac{L}{2}\right) \cdot D}{H_a} = \frac{(K_y + K_a) \cdot \left(\frac{L}{2}\right) \cdot D}{H_a}$$

$$\therefore R_{sum,parallel} = \frac{H_a}{(K_y + K_a) \cdot \left(\frac{L}{2}\right) \cdot D}$$

$$R_{cond,sandwich} = \frac{H_s}{K_s \cdot A_s} = \frac{H_s}{K_s \cdot L \cdot D}$$

$$R_{conv} = \frac{1}{h \cdot A_s} = \frac{1}{h \cdot L \cdot D}$$

$$R_{tot} = R_{sum,parallel} + R_{cond,sandwich} + R_{conv}$$

$$\therefore R_{tot} = \frac{H_a}{(K_y + K_a) \cdot \left(\frac{L}{2}\right) \cdot D} + \frac{H_s}{K_s \cdot L \cdot D} + \frac{1}{h \cdot L \cdot D} = \frac{1}{L \cdot D} \cdot \left[\frac{2 \cdot H_a}{(K_y + K_a)} + \frac{H_s}{K_s} + \frac{1}{h} \right]$$

(b)

$$q = \dot{q} \cdot V_{icepack} = \dot{q} \cdot L \cdot H_i \cdot D = (1.2 \text{ kW} / \text{m}^2) \cdot (0.25 \text{ m}) \cdot (0.03 \text{ m}) \cdot (0.25 \text{ m})$$

$$\boxed{\therefore q = 2.25 \text{ W}}$$

(c)

$$q = \frac{T_\infty - T_s}{R_{conv}}; \quad R_{conv} = \frac{1}{h \cdot A_s} = \frac{1}{h \cdot L \cdot D} = \frac{1}{(10 \text{ W} / \text{m}^2 - \text{K}) \cdot (0.25 \text{ m})^2} = 1.6 \text{ K} / \text{W}$$

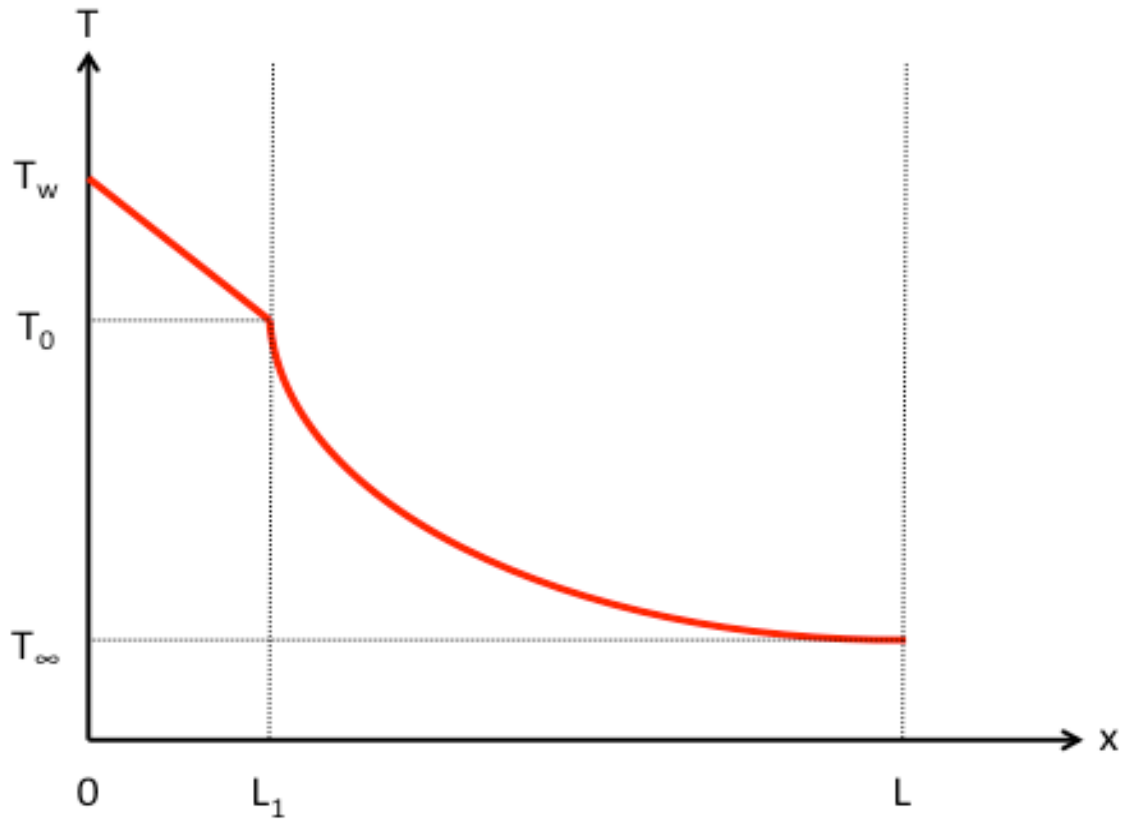
$$q = \frac{T_\infty - T_s}{R_{conv}} = \frac{(25^\circ\text{C} - T_s)}{1.6 \text{ K} / \text{W}} = 2.25 \text{ W}$$

$$T_s = 25^\circ\text{C} - (2.25 \text{ W}) \cdot (1.6 \text{ K} / \text{W})$$

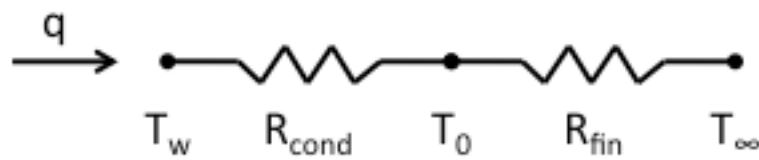
$$\boxed{\therefore T_s = 21.4^\circ\text{C}}$$

Problem 2

(a)



(b)



$$R_{cond} = \frac{L_1}{k \cdot A_c} = \frac{L_1}{k \cdot \frac{\pi D^2}{4}} = \frac{(0.2 \text{ m})}{(100 \text{ W / m-K}) \cdot \frac{\pi (0.025 \text{ m})^2}{4}} = 4.07 \text{ K / W}$$

$$q_{fin} = (h P k A_c)^{\frac{1}{2}} \cdot \theta_b = (h P k A_c)^{\frac{1}{2}} \cdot (T_0 - T_\infty) = \frac{(T_0 - T_\infty)}{(h P k A_c)^{-\frac{1}{2}}} = \frac{(T_0 - T_\infty)}{R_{fin}}$$

where

$$P = \pi D \quad \text{and} \quad A_c = \frac{\pi D^2}{4}$$

$$\begin{aligned} \therefore R_{fin} &= (h P k A_c)^{-\frac{1}{2}} = \left[(20 \text{ W/m}^2 - \text{K}) \pi (0.025 \text{ m}) (100 \text{ W/m} - \text{K}) \frac{\pi (0.025 \text{ m})^2}{4} \right]^{-\frac{1}{2}} \\ &= 3.6013 \text{ K/W} \end{aligned}$$

$$q = q'' \cdot A_c = (45 \times 10^3 \text{ W/m}^2) \cdot \frac{\pi (0.025 \text{ m})^2}{4} = 22.089 \text{ W}$$

$$q = \frac{T_0 - T_\infty}{R_{fin}} = \frac{T_0 - 25^\circ\text{C}}{3.6013 \text{ K/W}} = 22.089 \text{ W}$$

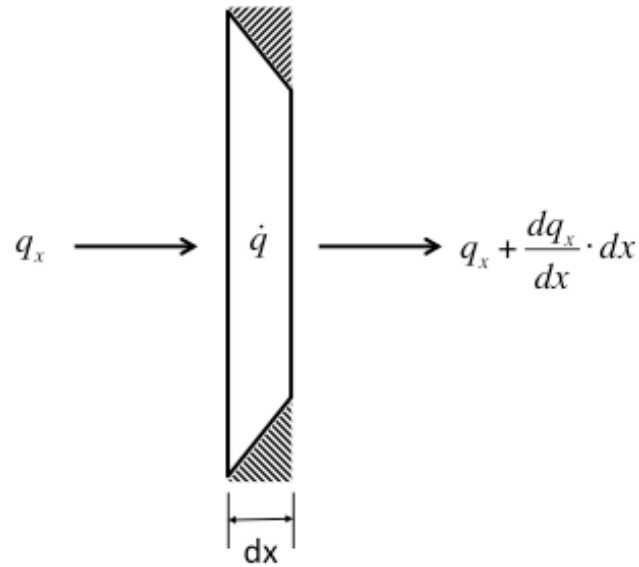
$$\boxed{\therefore T_0 = 104.55^\circ\text{C}}$$

$$q = \frac{T_w - T_0}{R_{cond}} = \frac{T_w - 104.55^\circ\text{C}}{4.07 \text{ K/W}} = 22.089 \text{ W}$$

$$\boxed{\therefore T_w = 194.45^\circ\text{C}}$$

Problem 3

(a)



Assumptions:

1. 1-D conduction
2. Steady state
3. Constant properties

$$\dot{E}_{in} - \dot{E}_{out} + \dot{E}_{gen} = \dot{E}_{store}$$

$$\dot{E}_{in} = q_x, \quad \dot{E}_{out} = q_x + \frac{dq_x}{dx} \cdot dx, \quad \dot{E}_{gen} = \dot{q} \cdot A(x) \cdot dx = \dot{q} \cdot A_0 e^{-ax} \cdot dx$$

$$\dot{E}_{store} = 0 \quad (\text{Steady state})$$

$$\dot{E}_{in} - \dot{E}_{out} + \dot{E}_{gen} = q_x - \left(q_x + \frac{dq_x}{dx} \cdot dx \right) + \dot{q} \cdot A_0 e^{-ax} \cdot dx = 0$$

$$\therefore q_x - \left(q_x + \frac{dq_x}{dx} \cdot dx \right) + \dot{q} \cdot A_0 e^{-ax} \cdot dx = 0$$

(b)

$$q_x - \left(q_x + \frac{dq_x}{dx} \cdot dx \right) + \dot{q} \cdot A_0 e^{-ax} \cdot dx = 0$$

$$-\frac{dq_x}{dx} \cdot dx + \dot{q} \cdot A_0 e^{-ax} \cdot dx = -\frac{dq_x}{dx} + \dot{q} \cdot A_0 e^{-ax} = 0$$

$$q_x = -k \cdot \frac{dT}{dx} \cdot A(x) = -k \cdot \frac{dT}{dx} \cdot A_0 e^{-ax}$$

$$\therefore -\frac{dq_x}{dx} + \dot{q} \cdot A_0 e^{-ax} = -\frac{d}{dx} \left(-k \cdot \frac{dT}{dx} \cdot A_0 e^{-ax} \right) + \dot{q} \cdot A_0 e^{-ax}$$

$$= k \cdot \frac{d}{dx} \left(\frac{dT}{dx} \cdot e^{-ax} \right) + \dot{q} \cdot e^{-ax} = \frac{d}{dx} \left(\frac{dT}{dx} \cdot e^{-ax} \right) + \frac{\dot{q}}{k} \cdot e^{-ax}$$

$$= \frac{d^2 T}{dx^2} \cdot e^{-ax} - a \cdot e^{-ax} \cdot \frac{dT}{dx} + \frac{\dot{q}}{k} \cdot e^{-ax}$$

$$= \frac{d^2 T}{dx^2} - a \cdot \frac{dT}{dx} + \frac{\dot{q}}{k} = 0$$

$$\boxed{\therefore \frac{d^2 T}{dx^2} - a \cdot \frac{dT}{dx} + \frac{\dot{q}}{k} = 0}$$

$$BC1: T_{x=0} = T_0$$

$$BC2: -k \frac{dT}{dx} \Big|_{x=L} \cdot A_{x=L} = h \cdot (T_{x=L} - T_\infty) \cdot A_{x=L}$$

$$\therefore -k \frac{dT}{dx} \Big|_{x=L} = h \cdot (T_{x=L} - T_\infty)$$